## User manual INDICATOR SWS-73

- Firmware: v.1.12 or higher
- Input type: RS-485
- Master / Slave function, two-colour display


Read the user's manual carefully before starting to use the unit or software.
Producer reserves the right to implement changes without prior notice.

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## Explanation of symbols used in the manual:

A- This symbol denotes especially important guidelines concerning the installation and operation of the device. Not complying with the guidelines denoted by this symbol may cause an accident, damage or equipment destruction.

## IF THE DEVICE IS NOT USED ACCORDING TO THE MANUAL THE USER IS RESPONSIBLE FOR POSSIBLE DAMAGES.

(i)- This symbol denotes especially important characteristics of the unit. Read any information regarding this symbol carefully

## 1. BASIC REQUIREMENTS AND USER SAFETY



- The manufacturer is not responsible for any damages caused by inappropriate installation, not maintaining the proper technical condition and using the unit against its destination.
- Installation should be conducted by qualified personnel. During installation all available safety requirements should be considered. The fitter is responsible for executing the installation according to this manual, local safety and EMC regulations.
- GND input of device should be connected to PE wire;
- The unit must be properly set-up, according to the application. Incorrect configuration can cause defective operation, which can lead to unit damage or an accident.
- If in the case of a defect of unit operation there is a risk of a serious threat to the safety of people or property additional, independent systems and solutions to prevent such a threat must be used.
- The unit uses dangerous voltage that can cause a lethal accident. The unit must be switched off and disconnected from the power supply prior to starting installation of troubleshooting (in the case of malfunction).
- Neighbouring and mating equipment must meet the requirements of appropriate standards and regulations concerning safety and be equipped with adequate anti-overvoltage and anti-interference filters.
- Do not attempt to disassemble, repair or modify the unit yourself. The unit has no user serviceable parts. Units, in which a defect was stated must be disconnected and submitted for repairs at an authorized service centre.
- In order to minimize fire or electric shock hazard, the unit must be protected against atmospheric precipitation and excessive humidity.
- Do not use the unit in areas threatened with excessive shocks, vibrations, dust, humidity, corrosive gasses and oils.
- Do not use the unit in areas where there is risk of explosions.
- Do not use the unit in areas with significant temperature variations, exposure to condensation or ice.
- Do not use the unit in areas exposed to direct sunlight.
- Make sure that the ambient temperature (e.g. inside the control box) does not exceed the recommended values. In such cases forced cooling of the unit must be considered (e.g. by using a ventilator).

The unit is designed for operation in an industrial environment and must not be used in a household environment or similar.

## 2. GENERAL CHARACTERISTICS

The SWS-73 is a simple digital panel indicator intended for displaying any numerical values and characters defined by user (in SLAVE mode only) sent from the master device over the RS 485 serial interface link. The displayed value may be collected from other device (in MASTER mode). The display brightness can be adjusted in 8 steps.

Modbus RTU protocol is used to communication with device. Baud rate is user defined in $1200 \div 115200$ baud range. It is possible to order device with other communication protocol using RS-485 interface (special order required).

## 3. TECHNICAL DATA

Power supply voltage (depending on version)
External fuse (required)
Power consumption

Power supply output
Display range

Communication interface
Baud rate
Display
(depending on version)
Data memory
85...230...260V AC/DC; $50 \div 60 \mathrm{~Hz}$ (separated) or 19...24...50V DC and 16...24...35V AC (separated) T - type, max. 2 A
max. 4.5 VA @ $85 \div 260 \mathrm{~V}$ AC/DC
max. 4.5 VA @ 16V $\div 35 \mathrm{~V}$ AC
max. 4.5 W @ 19V $\div 50 \mathrm{~V}$ DC
$24 \mathrm{~V}+5 \%,-10 \% / \max .100 \mathrm{~mA}$, stabilized
numerical and alphanumerical messages possible to show on 7-segment display

RS 485, 8N1 and 8N2, Modbus RTU, not separated $1200 \mathrm{bit} / \mathrm{s} \div 115200 \mathrm{bit} / \mathrm{s}$

LED, 4 digit, 13mm height, two-colour (red and green) or (for IP 65 version) 6 digit, 9 mm height, red non-volatile memory, EEPROM type

Protection level (depending on display size)
$5 \times 9 \mathrm{~mm}$ version: IP $65 \begin{gathered}\text { (from front), optional version with panel cut-out } \\ \text { sealing available }\end{gathered}$

$$
\text { IP } 20 \text { (housing and connection clips) }
$$

$4 \times 13 \mathrm{~mm}$ version: IP 40 (from front)
IP 20 (housing and connection clips)

Housing type
Housing material
Housing dimensions
Mounting hole
Assembly depth
Panel thickness
Operating temperature
(depending on version)
Storage temperature (depending on version)

Humidity
Altitude
Screws tightening max. torque
Max. connection leads diameter
Safety requirements

EMC
panel
NORYL - GFN2S E1
$72 \times 36 \times 97 \mathrm{~mm}$
$66.5 \times 32.5 \mathrm{~mm}$
min. 102 mm
max. 5 mm
$0^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}$
or $-20^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}$
$-10^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
or $-20^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$
5 to $90 \%$ no condensation
up to 2000 meters above sea level
0.5 Nm
$2.5 \mathrm{~mm}^{2}$
according to: PN-EN 61010-1
installation category: II
pollution degree: 2
voltage in relation to ground: 300 V AC
insulation resistance: $>20 \mathrm{M} \Omega$
insulation strength between power supply and
input/output terminal: 1min. @ 2300V
according to: PN-EN 61326-1

This equipment is not intended for use in residential environments and may not provide adequate protection to radio reception in such environments.

## 4. DEVICE INSTALLATION

The unit has been designed and manufactured in a way assuring a high level of user safety and resistance to interference occurring in a typical industrial environment. In order to take full advantage of these characteristics installation of the unit must be conducted correctly and according to the local regulations.

- Read the basic safety requirements on page 3 prior to starting the installation.
- Ensure that the power supply network voltage corresponds to the nominal voltage stated on the unit's identification label.
- The load must correspond to the requirements listed in the technical data.
- All installation works must be conducted with a disconnected power supply.
- Protecting the power supply clamps against unauthorized persons must be taken into consideration.


### 4.1. UNPACKING

After removing the unit from the protective packaging, check for transportation damage. Any transportation damage must be immediately reported to the carrier. Also, write down the unit serial number on the housing and report the damage to the manufacturer.

Attached with the unit please find:

- user's manual,
- warranty,
- assembly brackets - 2 pieces.


### 4.2. ASSEMBLY



- The unit is designed for mounting inside housings (control panel, switchboard) insuring appropriate protection against surges and interference. Metal housings must be connected to ground in a way that complies with the governing regulations.
- Disconnect the power supply prior to starting assembly.
- Check the connections are wired correctly prior to switching the unit on.

In order to install the unit, a $66.5 \times 32.5 \mathrm{~mm}$ mounting hole (Figure 4.1 ) must be prepared. The thickness of the material of which the panel is made must not exceed 5 mm . When preparing the mounting hole take the grooves for catches located on both sides of the housing into consideration (Figure 4.1). Place the unit in the mounting hole inserting it from the front side of the panel, and then fix it using the brackets (Figure 4.2). The minimum distances between the centre points of multiple units - due to the thermal and mechanical conditions of operation - are $91 \mathrm{~mm} x$ 57 mm (Figure 4.3).
a)

b)


Figure 4.1. Mounting hole dimensions: a) recommended b) allowable


Figure 4.2. Installing of brackets, and dimensions of connectors.


Figure 4.3. Minimum distances when assembly of a number of units

### 4.3. CONNECTION METHOD

## Caution



- Installation should be conducted by qualified personnel . During installation all available safety requirements should be considered. The fitter is responsible for executing the installation according to this manual, local safety and EMC regulations.
- The unit is not equipped with an internal fuse or power supply circuit breaker. Because of this an external time-delay cut-out fuse with minimal possible nominal current value must be used (recommended bipolar, max. 2A) and a power supply circuit-breaker located near the unit; In the case of using a monopolar fuse it must be mounted on the phase cable (L).
- The power supply network cable diameter must be selected in such a way that in the case of a short circuit of the cable from the side of the unit the cable shall be protected against destruction with an electrical installation fuse.
- Wiring must meet appropriate standards and local regulations and laws.
- In order to secure against accidental short circuit the connection cables must be terminated with appropriate insulated cable tips.
- Tighten the clamping screws. The recommended tightening torque is 0.5 Nm . Loose screws can cause fire or defective operation. Over tightening can lead to damaging the connections inside the units and breaking the thread.
- In the case of the unit being fitted with separable clamps they should be inserted into appropriate connectors in the unit, even if they are not used for any connections.


## - Unused clamps (marked as n.c.) must not be used for connecting any connecting cables (e.g. as bridges), because this can cause damage to the equipment or electric shock.

- If the unit is equipped with housing, covers and sealing packing, protecting against water intrusion, pay special attention to their correct tightening or clamping. In the case of any doubt consider using additional preventive measures (covers, roofing, seals, etc.). Carelessly executed assembly can increase the risk of electric shock.
- After the installation is completed do not touch the unit's connections when it is switched on, because it carries the risk of electrical shock.

Due to possible significant interference in industrial installations appropriate measures assuring correct operation of the unit must be applied. To avoid the unit of improper indications keep recommendations listed below.

- Avoid common (parallel) leading of signal cables and transmission cables together with power supply cables and cables controlling induction loads (e.g. contactors). Such cables should cross at a right angle.
- Contactor coils and induction loads should be equipped with anti-interference protection systems, e.g. RC-type.
- Use of screened signal cables is recommended. Signal cable screens should be connected to the earthing only at one of the ends of the screened cable.
- In the case of magnetically induced interference the use of twisted couples of signal cables (so-called "spirals") is recommended. The spiral (best if shielded) must be used with RS-485 serial transmission connections.
- In the case of measurement or control signals are longer than 30 m or go outside of the building then additional safety circuits are required.
- In the case of interference from the power supply side the use of appropriate antiinterference filters is recommended. Bear in mind that the connection between the filter and the unit should be as short as possible and the metal housing of the filter must be connected to the earthing with largest possible surface. The cables connected to the filter output must not run in parallel with cables with interference (e.g. circuits controlling relays or contactors).

Connections of power supply voltage and controlling signals are executed using the screw connections on the back of the unit's housing.


Figure 4.4. Method of cable insulation replacing and cable terminals


Figure 4.5. Terminals description
All connections must be made while power supply is disconnected!


Figure 4.6. Connection of power supply

### 4.4. MAINTENANCE

The unit does not have any internal replaceable or adjustable components available to the user. Pay attention to the ambient temperature in the room where the unit is operating. Excessively high temperatures cause faster ageing of the internal components and shorten the fault-free time of unit operation.
In cases where the unit gets dirty do not clean with solvents. For cleaning use soft, dry cloth. In the case of more significant contamination use warm water with small amount of detergent to wet the cloth.

Using any other agents can cause permanent damage to the housing.

Product marked with this symbol should not be placed in municipal waste. Please check local regulations for disposal and electronic products.

## 5. FRONT PANEL DESCRIPTION



Symbols and functions of push-buttons:

Symbol used in the manual: [ESC/MENU] Functions:

- Enter to main menu ( press and hold by at least 2 sec.)
- Exit the current level and Enter to previous menu (or displaying mode)
- Cancel the changes made in parameter being edited

Symbol used in the manual: [ENTER]

## Functions:

- Start to edit the parameter
- Enter to the sub-menu,
- Confirmation of changes made in parameter being edited


Symbol used in the manual: [^] [v]
Functions:

- Change of the present menu,
- Modification of the parameter value,
- Change of the display mode.

Inactive.

## 6. PRINCIPLE OF OPERATION

After turning the power supply on, device ID and software version are showed on the display, next the digital indicator goes to the display mode.

### 6.1. DISPLAYING MODE

Directly after enter to displaying mode, device displays "- - -" info as long as first actualization of displayed value via RS-485 interface comes. Depend on value of "modE" parameter of "rS" menu, device can works as MASTER or SLAVE. In SLAVE mode displayed value, and it's parameters are determined by values written to internal registers by other MASTER. In MASTER mode device reads values to displaying, and it's decimal point position from selected SLAVE device.

If content of displayed value register exceeds permissible displaying range following message is showed:

- "ovH" - if content displayed value register exceeds upper border of of permissible displaying range
- "ovL" - if content displayed value register is smaller than lower border of permissible displaying range

Permissible displaying range depends on number of available decades and equals:

- -999 $\div 9999$ for devices equipped with 4 decades,
- $-99999 \div 999999$ for devices equipped with 6 decades.

All accessible parameters can be changed by entering the menu (see: DEVICE PROGRAMMING). Use the local keyboard or the remote controller to do it. (Note: all parameters can be remote changed via RS-485 interface).

(i)Configuration of the device (via menu or RS 485 interface) do not stops device.

### 6.1.1. SLAVE mode operation

In SLAVE mode device displays "- - _" info as long as first write to displayed value registers by MASTER device comes over RS-485 interface. If new value will not be written in this register in time defined by "mbtO" parameter since last writing, currently displayed value starts blinking. It stops blinking after next proper write. SLAVE mode allows display user defined signs on selected positions (see: DRIVING OF DECADES, page 23). Parameters connected with SLAVE mode are accessible in menu "SLAv", which is displayed only if SLAVE mode is selected (see "modE" parameter in "rS" menu).

### 6.1.2. MASTER mode operation

In MASTER mode device displays "- - - -" info as long as first read of selected registers of SLAVE device occurs. If SLAVE device do not responds during time defined by "mbtO" parameter, since MASTER sent last frame, currently displayed value starts to blinking. Blinking stops after next proper read of selected register of SLAVE device. Registers of SLAVE device are read every time defined by parameter "PEr". Parameters connected with MASTER are accessible in menu "mASt", which is displayed only if MASTER mode is selected (see "modE" parameter in "rS" menu).

## 7. DEVICE PROGRAMMING

The device menu allow user to set all parameters connected to operation of the display, control modes, communication via RS-485 and access settings. The meaning of the particular parameters is described in paragraph MENU DESCRIPTION.

### 7.1. PROGRAMMING MENU

To enter main menu (being in the displaying mode) operator must to press and hold at least 2 sec . [ESC/MENU] button.

If the user password is defined (see parameter "Scod"), operator have to enter correct one before proceeding to menu options. Entering of the passwords is similar to the edition of numeric parameters (see: PARAMETERS EDITION ), however presently editing digit is showed only on the display, other digits are replaced by "-" sign.

After entering of last digit of the password first menu position will be displayed (if the password is correct) or warning "Err" in other case.

## Functions of the buttons while sub-menu and parameters choice:



Selection of sub-menu or parameter for editing. Name of selected item (submenu or parameter) is displayed.

Operation of [ENTER] button depend on present menu position:

- if the name of some sub-menu is displayed - enter this sub-menu; name of the first parameter (or next level sub-menu) is displayed,
- if the name of some parameter is displayed - enter the edition of this parameter; present value of the parameter is displayed,
[ESC/MENU] button allow user to exit present menu level and goes to upper level menu (or displaying mode).

(i)After about 1 min . since last use of the buttons, device exits the menu mode and returns to the displaying mode (only if no parameters are in editing mode).

### 7.2. PARAMETERS EDITION

To start edition of any parameter user should select name of desired one using [^] [v] buttons and then press [ENTER].

### 7.2.1. Numeric parameters (digit change mode)

Numerical parameters are displayed as decimal numbers. The mode of its new value entering depends on chosen edit method ( see parameter „Edit").

In mode "by digit" („Edit"="dig") pressing one of the keys [^] or [v] causes change of current position (flashing digit) or the sign (+/-). Short pressing of the [ENTER] button causes change of the position (digit).

Press [ENTER] at least 2 seconds to accept the changes, after that question "SEt?" is displayed, and user must to confirm (or cancel) the changes. To conform changes (and story it in EEPROM) press [ENTER] button shortly after "SEt?" is displayed. To cancel the changes press [ESC] button shortly after "SEt?" is displayed. After that device returns to the menu.

### 7.2.2. Numeric parameters (slide change mode)

In "slide change" mode („Edit"="Slid"), buttons [^^] and [v] has different functions.
To increase edited value press (or press and hold) [^] button only, the increasing became quickest as long as button [^] is pressed. To slow down the increasing, button [v] can be used. If [ $\mathbf{v}$ ] is pressed shortly (and button [^] is still pressed), increasing slow down for a moment only, if [ $\mathbf{v}$ ] is pressed and held while button [^] is still pressed the increasing slow down and will be kept on lower speed.

To decrease edited value press (or press and hold ) [v] button only. The decreasing became quickest as long as button [v] is pressed. To slow down the decreasing, button [^] can be used. If [ ${ }^{\wedge}$ ] is pressed shortly (and button [ $\mathbf{v}$ ] is still pressed), decreasing slow down for a moment only, if [^] is pressed and held while button [ v ] is still pressed the decreasing slow down and will be kept on lower speed.

Press [ENTER] at least 2 seconds to accept the changes, after that question "SEt?" is displayed, and user must to confirm (or cancel) the changes. To conform changes (and story it in EEPROM) press [ENTER] button shortly after "SEt?" is displayed. To cancel the changes press [ESC] button shortly after "SEt?" is displayed. After that device returns to the menu.

### 7.2.3. Switch parameters ("LIST" type)

Switch parameters can be described as a sets of values (a lists) out of which only one of the options available on the list can be selected for the given parameter. Options of switching parameter are selected using [^], [v] keys.

Short pressing of [ENTER] causes in displaying of the acknowledge question ("SEt?"). If key [ENTER] is pressed again, the changes are accepted, stored in EEPROM end the edition process finished. Pressing the key [ESC] after "SEt?" causes in cancelling of made changes and returning to menu.

## Functions of buttons when editing numeric and switching parameters:



While editing numeric parameter:

- change of current (flashing) digit
- slide change of value (acceleration, deceleration, direction change) While editing switch parameter - selection of switch parameter.

If numerical parameter is being edited, a short press of [ENTER] button change edited position. A long press of [ENTER] button (at lest 2 sec .) causes of display a "SEt?" ask, which allow user to make sure if change of the parameter value is correct. If switch parameter is being edited, a short press of [ENTER] button causes of display a "SEt?" ask. When [ENTER] button is pressed again (while "SEt?" is displayed) the new value of the parameter is stored in EEPROM memory.

Pressing this button operator can cancel the changes done up to now (if they were not approved by [ENTER] button after the "SEt?" ask) and come back to menu

### 7.3. MENU DESCRIPTION

"- - - -" - password checking. If some password different from „0000" is set, then every enter to main menu follows the entering of password. If entered password is correct then first menu position will be displayed else warning "Err", and unit returns to displaying mode.

(i)Due to problem with direct displaying of "m" letter, it is exchanged with special sign " $\overline{\boldsymbol{n}}$ ". Independently in user manual letter „ $\mathbf{m}$ " is used to make it more readable (example: "modE").

### 7.3.1. "bri" parameter

This parameter allows user to set bright of the LED display, bright can be set to conventional values from "bri1" to "bri8".

### 7.3.2. "col" parameter

This option allows changes colour of displayed signs. Possible values: "rEd" - red, "grEE" green
(1) This parameter occurs only in 4 decade version.

### 7.3.3. "SLAv" menu

This menu is accessible only if SLAVE mode is selected, and it contains parameters connected with this mode:
"Addr" - this parameter defines the address of the device, accordingly to Modbus protocol. It can be set in range from 0 to 199. If the value 0 is set then device, responds to frames with address 255 (FFh).

1 In SLAVE mode every SWS-73 connected to the same serial network should have its own address, different from other devices addressed.
"tyPE" - type of value written to displayed value registers, it can be set to:
" $U-16$ " - unsigned 16 bit (write to register 01h is not necessary);
"S-16" - signed 16 bit (write to register 01h is not necessary);
"U-32" - unsigned 32 bit (writes to registers 01h and 02h are necessary);
"S-32" - signed 32 bit (writes to registers 01h and 02h are necessary);
"mbAc" - this parameter sets the access to the configuration registers of the device. Possible values:
"on" - configuration registers can be set via RS-485 interface,
"oFF" - configuration registers can not be set via RS-485 interface.

(i)
Blockade of writing do not refers with registers no. 01h, 02h i 03h (see: LIST OF REGISTERS).
"vALr"

- this parameter defines reaction for writes to registers $01 \mathrm{~h}, 02 \mathrm{~h}$ and 03 h , it can be set to:
"on" - after writes device responds with standard frame
"oFF" - after writes device do not sends anything.

(i)
If parameter "vALr" is set to "oFF", then it is possible to drive many devices simultaneously (at the same moments), without collisions in network.

### 7.3.4. 'mASt" menu

This menu is accessible only if MASTER mode is selected, and it contains parameters connected with this mode:
"Addr" - this parameter defines the address of the device which have to be read. It can be set in range from 0 to 199. If the value 0 is set then device with address 255 (FFh) will be read.
"rEG" - this parameter defines holding register number (of SLAVE device), which contains displayed value. If displayed value type is set as 32 bits (signed or unsigned - see parameter "tyPE", parameter "rEG" defines higher word register address. Its value can be changed from 0 to 9999.
"tyPE" - type of value written to displayed value registers, it can be set to:
" $U$-16" - unsigned 16 bit (single register);
"S-16" - signed 16 bit (single register);
" $U$-32" - unsigned 32 bit (two following registers);
"S-32" - signed 32 bit (two following registers);
"Pnt" - decimal point position, following values are possible for this parameter " 0", " 0.0", " 0.00",..., "rEG ".
If value "rEG" is selected, then decimal point position will be read from holding register defined by parameter "PrEG" of SLAVE device defined by parameter "Addr"
"PrEG" - this parameter defines holding register number (of SLAVE device) which contains decimal point position. Value of this parameter matters only if parameter "Pnt" is set to value "rEG". In other case value of "PrEG" does not matter.
"PEr" - this parameter defines time period between successive reads of displayed value and decimal point position (if "Pnt"="rEG") registers.

### 7.3.5. "rS" menu

This menu is connected with RS-485 interface, and sets his properties:
"modE" - this parameter defines device operation mode. There are available two modes:
"mASt" - MASTER mode operation. SWS-73 unit reads necessary data from defined registers of SLAVE device. All parameters referred with this operation mode are available in "mASt" submenu;
"SLAv" - SLAVE mode operation, SWS-73 unit waits for data from MASTER device. All parameters referred with this operation mode are available in "SLAv" submenu;
"bAud" - this parameter determines RS-485 interface baud rate. It can be set to one of 8 possible values: "1.2", "2.4", "4.8", "9.6", "19.2", "38.4","57.6","115.2", which respond to the baud rates of 1200, 2400, 4800, 9600, 19200, 38400, 57600 and 115200 bit/s respectively.
"mbtO" - this parameter defines maximal time (sec) between following frames received by the device. If the delay will be greater than the value of "mbtO" parameter, displayed value starts blinking. Parameter "mbtO" can be set to values from 0 to 99 seconds. The value 0 means that the time will be not controlled.

In MASTER mode, time period defined by parameter "mbtO" is prolonged of value defined by parameter "PEr".
"rESP" - this parameter defines minimal (additional) delay between the Modbus message and the answer of the device (received and sent via RS-485 interface). This additional delay allows the device to work with poor RS-converters which do not works properly on baud rates higher than 19200. This parameter can be set to one of values:
"Std" - answer as quick as possible, no additional delay
"10c"
" 20 c "
" 50 c" "100c"

- answer delayed of 10, 20, 50, 100 of 200 chars respectively, where one character time depends on selected baud rate
(i)

In the most cases parameter "rESP" should be set to "Std" (no additional delay). Unfortunately for some third party RS-converters "rESP" should be adjusted experimentally. Table 7.1 contains most frequently used values.

| "bAud" parameter | "38.4" | " $57.6 "$ | $" 115.2 "$ |
| :---: | :---: | :---: | :---: |
| "rESP" parameter | "10c" | " $20 \mathrm{c} "$ | " $50 \mathrm{c} "$ |

Tab.7.1. Settings of "rESP" parameter

### 7.3.6. "Scod" parameter

This parameter defines user password (4-digits number). If this parameter is set at value "0000", user password is turned off.

If the user do not remember his password, the access to the menu is possible by the "one-use password". To get this password please contact with Marketing Division. "Single use password" can be used only one time, after that it is destroyed. Entering this password causes in clearing of user password, it means sets the user password to „0000".

(1)
The "one-use password" can be used ONE TIME ONLY, it is impossible to use it again! The "one-use password" can be restored by Service Division only.

### 7.3.7. "Edit"' parameter

This parameter allows to change the edition mode of numerical parameters:
"dig" - the change to "by digit" mode,
"Slid" - slide change mode.

### 7.3.8. "dEFS" parameter

This setting allows to restore the factory settings of the device. To get the access to this option special password is required: „5465", next the device displays acknowledge question „SEt?". Press [ENTER] to acknowledge the restoring of factory settings or [ESC] to cancel.

### 7.3.9. "SErv" menu

This menu contains the parameters for authorized service only. To enter this menu proper service password must be entered. Improper settings can causes of damage of the device.

### 7.4. MENU STRUCTURE



## 8. THE MODBUS PROTOCOL HANDLING

Transmission parameters: 1 start bit, 8 data bits, 1 or 2 stop bit ( 2 bits are send, 1 and 2 bits are accepted when receive), no parity control
Baud rate:
Transmission protocol: selectable from: 1200 to 115200 bits/second MODBUS RTU compatible

The device parameters and display value are available via RS-485 interface, as HOLDINGtype registers (numeric values are given in U2 code) of Modbus RTU protocol. The registers (or groups of the registers) can be read by 03h function, and wrote by 06 h (single registers) or 10h (group of the registers) accordingly to Modbus RTU specification. Maximum group size for 03 h and 10 h functions can not exceeds 16 registers (for single frame).

The device interprets the broadcast messages, but then do not sends the answers.

### 8.1. LIST OF REGISTERS

| Register | Write | Range | Register description |
| :---: | :---: | :---: | :---: |
| 01h | Yes | see descr. | Displayed value - higher word. <br> Warning! To change displayed value it is required to write data in following manner: first higher word and next lower word of data. Writing of higher word only do not causes changes in displayed data. |
| 02h | Yes |  |  |
|  |  |  | Displayed value - lower word. <br> Total value of registers 01h and 02h: from -999 to 9999 (for 4 decade version) or from -99999 to 999999 (for 6 decade version); data type depends on parameter "tyPE" of "SLAv" submenu. |
| 03h | Yes | see descr. | Higher byte - displaying mode of registers 01 h i 02 h content: $\mathbf{0 0 h}$ - display value of registers 01 h i 02 h as a digits, with control of range. If allowable range ( from -999 to 9999 for 4 decade version or from -99999 to 999999 for 6 decade version) is exceeded then proper warning is displayed ("ovH" or "ovL"); <br> 80h - display "-Hi-" rather than value of registers 01 h i 02 h ; <br> 40h - display "-Lo-" rather than value of registers 01h i 02h; <br> Lower byte: <br> bit 7 -reserved <br> bits $6 . .4$ - minimal number of displayed digits. <br> $\mathbf{0}$ - one digit; 1 - two digits; etc. (see Tab. 8.1). If content of registers 01 h and 02 h is shorter than minimal number of digits, then <br> additional 0's are displayed. <br> bit 3 - display decimal point on most right position regardless of bits $2 . .0$ value <br> bits 2.0 - decimal point position: <br> 0 - no decimal point; 1 - " 0.0"; 2 - " 0.00"; etc. |
| 04h | Yes | see descr. | Lower byte - shift of displayed value to the left of the display - bits $3 . .0$ defines shift size ( 0 - no shift; 1 - one position; etc.) |


| Register | Write | Range | Register description |
| :---: | :---: | :---: | :--- |


| Register | Write | Range | Register description |
| :---: | :---: | :---: | :---: |
| $23 h^{3}$ | Yes | $0 \div 1$ | "mbAc" parameter in "SLAv" menu (permission to write registers via RS-485 interface); $\mathbf{0}$ - write denied ; $\mathbf{1}$ - write allowed |
| 25h | Yes | $0 \div 5$ | "rESP" parameter in "rS" menu (additional response delay); 0 - no additional delay; 1 - "10c" option; 2 - "20c" option; <br> 3 - "50c" option; 4 - "100c" option; 5 - "200c" option; |
| 26h | Yes | $0 \div 1$ | "vALr" parameter in "SLAv" menu ( blockade of modbus answer, after writes to registers $01 \mathrm{~h}, 02 \mathrm{~h}$ or 03 h ); <br> 0 - answer blocked; 1 - standard modbus answer |
| 27h | Yes | $0 \div 99$ | "mbtO" parameter in "rS" menu (maximum delay between received frames); $\mathbf{0}$ - no delay checking; <br> $1 \div 99$ - maximum delay expressed in seconds |
| 2Dh ${ }^{4}$ | Yes | $1 \div 8$ | "bri" parameter (display brightness); <br> 1 - the lowest brightness; 8 - the highest brightness |
| $2 E h^{4}$ | Yes | $0 \div 1$ | "col" parameter (display colour) - for 4 decade with two-color display version only: <br> 0 - green; 1 - red |
| 2Fh | Yes | $0 \div 1$ | "Edit" parameter (numerical parameters edit mode); 0-„dig" mode; 1 - „SLid" mode |
| 30h | Yes | $0 \div 3$ | "tyPE" parameter in "SLAv" menu (displayed value type): <br> 0 - unsigned 16 bit (write to register 01h is not necessary); <br> 1 - signed 16 bit (write to register 01h is not necessary); <br> 2 - unsigned 32 bit (writes to registers 01 h and 02 h are necessary); <br> 3 - signed 32 bit (writes to registers 01 h and 02 h are necessary); |
| $31 \mathrm{~h}^{4}$ | Yes | $1 \div 8$ | Dynamically driving of display brightness via serial interface |
| $32 h^{4}$ | Yes | $0 \div 8$ | Dynamically driving of display colour via serial interface - for 4 decade with two-color display version only: <br> 0 - green; 1 - red |

1 - after writing to register no 20h the device responds witch an "old" address in the message.
2 - after writing to register no 22 h the device responds with the new baud rate.
3 - the value of the "mbAc" parameter is also connected to write to this register, so it is possible to block a writes, but impossible to unblock writes via RS-485 interface, The unblocking of the writes is possible from menu level only.
4 - if often changing of display colour or brightness is required, writing to registers 31 h and 32 h is recommended. Contents of those registers are not stored while power off, and after power on parameters set via MENU are used for display colour and brightness (registers 2Dh and 2Eh)

### 8.2. TRANSMISSION ERRORS DESCRIPTION

If an error occurs while write or read of single register, then the device sends an error code according to Modbus RTU specifications.

## Error codes:

01h - illegal function (only functions 03h, 06h and 10h are available),
02h - illegal register address
03h - illegal data value
08h - no write permission ( see: "mbAc" parameter)

### 8.3. DRIVING OF DECADES

(i)

- Driving of decades described below is possible in SLAVE mode only
- Number of available decades depends on device type


Figure 8.1. Decades positions for 6 decade version

### 8.3.1. Decimal point position and minimal number of digits

| Bits 6..0 of register. 03h <br> (example value) | Displayed message if <br> „displayed value" equals 1 | Displayed message if <br> „displayed value" equals 123 |
| :---: | :---: | :---: |
| 0000000 | 1 | 123 |
| 0000001 | 0.1 | 12.3 |
| 0000010 | 0.01 | 1.23 |
| 0000011 | 0.001 | 0.123 |
| 0001 xxx | 1. | 123. |
| 0100000 | 01 | 123 |
| 0100001 | 0.1 | 12.3 |
| 0100010 | 0.01 | 1.23 |
| 0101 xxx | 01. | 123. |
| 1000000 | 0001 | 0123 |
| 1000001 | 000.1 | 012.3 |
| 1000010 | 00.01 | 01.23 |
| 1001 xxx | 0001. | 0123. |
| 200 |  |  |

$x$ - does not matter
Tab. 8.1. Decimal point position and minimal number of digits

### 8.3.2. Interpretation of registers $10 \mathrm{~h} . .15 \mathrm{~h}$ content

Con - if this bit is set (1) then, sign defined by bits $7 . .0$ is displayed in place of particular digit (defined as a part of registers 01 h and 02 h value),

Asc - if this bit is set then sign to be placed on particular decade (defined by bits $7 . .0$ ) is interpreted as ASCII code,

X $\quad$ - these bits does not matter
DP, G...A - these bits defines if particular segments light or not (only if bit Asc=0) or ASCII code of particular decade (only if bit Asc=1).

| $\mathbf{1 5}$ | $\mathbf{1 4}$ | $\mathbf{1 3 . 8}$ | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Con | Asc | X | DP | G | F | E | D | C | B | A |



Tab. 8.2. Interpretation of registers $10 \mathrm{~h} . . .15 \mathrm{~h}$ content

### 8.3.3. Interpretation of registers 18 h ... 1Dh content

X $\quad$ - these bits does not matter
BL - if this bit is set then particular decade blinks about time per second

| $15 . .13$ | 12 | $11 . .0$ |
| :---: | :---: | :---: |
| X | BL | X |

Tab. 8.3. Interpretation of registers 18h ... 1Dh content

### 8.3.4. Examples of exploration of registers $02 h$ and $03 h$

To display 16 bit signet numbers, with 2 digits after decimal point. Parameter "tyPE" of menu "SLAv" should be set to " $\mathrm{S}-16$ " ( 16 bit signed values). To set decimal point position, the value of register 03 h must to be written with value 2 (see Tab. 8.1). Decimal point position can be done once, and it is valid for all further values of reg. 01 h and 02 h .

To set displayed value, its value must to be written to register 01h and 02h, e.g.

- by writing of $0010 \mathrm{~h}(+16$ decimal) to register 02 h (reg. $01 \mathrm{H}=0000 \mathrm{~h}$ ) causes by displaying:

- by writing values higher than permissible displaying range causes by displaying:

- by writing values lower than permissible displaying range causes by displaying:

(i) Displaying of negative numbers is possible only if proper displaying value data type is selected („S-32" or „S-16"). Negative values should be written in U2 code.


### 8.3.5. Examples of exploration of registers $10 \mathrm{~h} . . .15 \mathrm{~h}$

To display message like showed hereafter, with assumption that number value (6.5) may be changed (e.g. depend on measurement value):

### 6.50 C

User should set:

1. register 02 h to value 0021 h ( 65 decimal)
2. register 03h (decimal point position) to value 0001h (see Tab. 8.1),
3. register 10h (sign in place of decade 1) to value C043h (ASCII code of "C" sign in lower byte and bits Con i Asc in higher byte, see Tab. 8.2),
4. register 11h (sign in place of decade 2) to value 8063h (byte code of „" "sign in lower byte, and bit Con in higher byte - no ASCII coding - see Tab. 8.2),
5. register 04 h (left shift of displayed value) to value 02 h (shift of 2 positions to the left).

Writes presented above can be done at once, and it is valid for all further values of reg. 01 h and 02 h .

To change displayed number (6.5) it is change of register 02h only is necessary (if data type is set to 16 bits ), e.g. By writing of value 12 to reg. 02h causes by displaying message:

$$
1.200
$$

User must to remember, that signs defined by registers 10h...13h will be displayed in place of particular digits of displayed values, e.g. If in example above user writes value C041h (sign „A" in ASCII code) to register 12h, then device shows message:
8.4. EXAMPLES OF QUERY/ANSWER FRAMES

Examples apply for device with address 1 . All values are represent hexadecimal.
Field description:
ADDR Device address on modbus network
FUNC Function code
REG H,L Starting address (address of first register to read/write, Hi and Lo byte)
COUNT H,L No. of registers to read/write (Hi and Lo byte)
BYTE C Data byte count in answer frame
DATA H,L Data byte (Hi and Lo byte)
CRC L,H CRC error check (Hi and Lo byte)

## 1. Read of device ID code

| ADDR | FUNC | REG H,L |  | COUNT H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 03 | 00 | 21 | 00 | 01 | D4 | 00 |

The answer:

| ADDR | FUNC | BYTE C | DATA H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 03 | 02 | 20 | EF | E0 | 08 |

DATA - identification code (20EFh)
2. Change of the device address from 1 to 2 (write to reg. 20h)

| ADDR | FUNC | REG H,L |  | DATA H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 06 | 00 | 20 | 00 | 02 | 09 | C1 |

DATA H-0
DATA L - new device address (2)
The answer (the same as the message):

| ADDR | FUNC | REG H,L |  | DATA H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 06 | 00 | 20 | 00 | 02 | 09 | C1 |

3. Writing of value to be displayed, and decimal point position (multi register write using modbus function 10h)

| ADDR | FUNC | REG H,L |  | COUNT H,L |  | BYTE C |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 10 | 00 | 01 | 00 | 03 | 06 |

And next bytes of frame:

| DATA H1,L1 |  | DATA H2,L2 |  | DATA H3,L3 |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 00 | 00 | 04 | D2 | 00 | 02 | 97 | $8 D$ |

This write causes by displaying message: "12.34"
Device's answer:

| ADDR | FUNC | REG H,L |  | COUNT H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 10 | 00 | 01 | 00 | 03 | D1 | C8 |

4. Try to write improper value to register 22 h (baud rate).

| ADDR | FUNC | REG H,L |  | DATA H,L |  | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | 06 | 00 | 22 | 00 | 09 | E9 | C6 |

DATA L - DATA L - value exceeds allowable range (from 0 to 7 )
The answer (if an error occur):

| ADDR | FUNC | ERR | CRC L,H |  |
| :---: | :---: | :---: | :---: | :---: |
| 01 | 86 | 03 | 02 | 61 |

(i)
There is no full implementation of the Modbus Protocol in the device. The functions presented above are available only.

## 9. DEFAULT AND USER'S SETTINGS LIST

| Parameter | Description | Default value | User's value | Desc. page |
| :---: | :---: | :---: | :---: | :---: |
| bri | Display brightness | bri6 |  | 15 |
| col | Display colour | grEE |  | 15 |
| Configuration of SLAVE mode (menu "SLAv") |  |  |  |  |
| Addr | SWS-73 device address | 0 |  | 15 |
| tyPE | Display value type | S-16 |  | 15 |
| mbAC | Permission to changes of configuration registers | on |  | 15 |
| vALr | Blockade of answer after writes to reg. 01H , 02h or 03h | on |  | 16 |
| Configuration of MASTER mode ("mASt" menu) |  |  |  |  |
| Addr | SLAVE device address | 0 |  | 16 |
| rEG | Number of displayed value register | 1 |  | 16 |
| tyPE | Displayed value data type | S-16 |  | 16 |
| Pnt | Decimal point position | 0 |  | 16 |
| PrEG | Decimal point register number (of SLAVE device) | 5 |  | 16 |
| PEr | Time period of data reading from SLAVE device | 0 |  | 16 |
| RS 485 interface configuration ("rS" menu) |  |  |  |  |
| modE | Operation mode | SLAv |  | 17 |
| bAud | Baud rate | 9600 |  | 17 |
| mbtO | Maximum delay between received messages | 0 |  | 17 |
| rESP | Additional delay of answer transmission | Std |  | 17 |
| Configuration of numerical parameters edition |  |  |  |  |
| Edit | Numerical parameters edit mode | dig |  | 18 |



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